## **Operation Instructions**

Multi-purpose microwave motion sensor

## **Argus Radar 2**



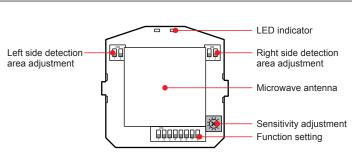


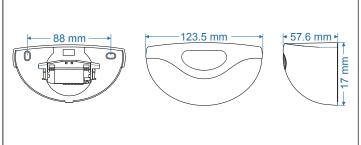
### 1 Safety Instruction



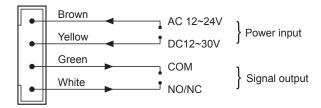
Thank you very much for purchasing this product, in order to use it correctly, please read this manual instruction carefully before use.

### 2 Product Overview





### 3 Wiring Definition



### 4 Installation

# Insert a screwdriver into the opening slot and gently lever it, then remove the cover. Install The Sensor Tight The Cover Install The sensor in the appropriate position, mark the holes; 2. Drilling the holes, and thread the wire through the holes. Install The Sensor Tight The Cover Install The Sensor Insert the cover into the top of the sensor, press it down until they are tight.

### Installation precautions



Fix the sensor tightly to avoid vibrating



Sensors should not be placed behind the shield.



Moving objects should be avoided



Fluorescent source can't be present



Do not touch directly, ESD Protection is necessary



Before the device is powered on, clear other objects in the sensing area that not belong to the area.

### 5 Detection Range Setting

### Vertical depth sensing adjustment









The depth sensing adjustment can be modified in 12° increments. Grasp the pivot handles on two sides of the sensor base and twist forward and backward to position as desired (factory default is 36°).

Note: Don't touch the microwave antenna directly with your hands during adjustment, as this may cause static electricity damage. Please adjust it using the pivot handle.

## Right side detection area adjustment (Narrowest) (Narro

### 6 Function setting DIP switch

| 1<br>Direction    | Bidirectional induction  | *        | Close, far away, lateral movement can be detected.                   |  |
|-------------------|--------------------------|----------|--|--|
|                   | Unidirectional induction | 1        | Close, lateral movement can be detected, far away won't be detected. |  |
| <b>2</b><br>Relay | <b>↓</b> NO              | <b>\</b> | Normally open output.  |  |
|                   | nc nc                    | 7        | Normally close output.   |  |



| 3                             | Ţ          | OFF     | ••••       | Normal default.  |                    |   |  |  |
|-------------------------------|------------|---------|------------|--|--------------------|---|--|--|
| Anti-interference             | <u>†</u>   | ON      | ****       | Used to reduce interference such as rain, vibration and reflection.  |                    |   |  |  |
| 4                             | Ţ          | OFF     |            | When the movement speed is too slow, it will be filtered and won't be detected.  |                    |   |  |  |
| Low speed                     | Î          | ON      | $\bigcirc$ | Slow speed can also be detected, but the lateral suppression effect will be weakened.  |                    |   |  |  |
| 5 6<br>Lateral<br>suppression | ŢŢ         | NONE    | -          | -  | Width of induction | This function only works for unidirectional induction. When the lateral suppression function is used, the system ignores the DIP NO.1 selection and forces unidirectional induction. With three levels different induction effect, induction width is also different. |  |  |
|                               | <b>↑</b> ↓ | Level 1 |            | Light filter   | 2.5m               |   |  |  |
|                               | <b>I</b>   | Level 2 |            | Medium filter  | 2.1m               |   |  |  |
|                               | ††         | Level 3 |            | Strong filter  | 1.3m               |   |  |  |
| 7 8<br>Output hold            | ŢŢ         | 1 sec   | <u></u>    | The system detects the moving object, it will trigger the signal output, until the object is stationary for 1 second, will stop the signal output. |                    |   |  |  |
|                               | <b>1</b>   | 2 sec   | <b></b>    | The system detects the moving object, it will trigger the signal output, until the object is stationary for 2 second, will stop the signal output. |                    |   |  |  |
|                               | <b>I</b>   | 3 sec   | <u>3</u>   | The system detects the moving object, it will trigger the signal output, until the object is stationary for 3 second, will stop the signal output. |                    |   |  |  |
|                               | <b>1</b> 1 | 5 sec   | 5"         | The system detects the moving object, it will trigger the signal output, until the object is stationary for 5 second, will stop the signal output. |                    |   |  |  |

### 7 Sensitivity adjustment



Clockwise adjustment, high sensitivity, counterclockwise adjustment, low sensitivity. A total of 10 levels adjustable.

### 8 Fault Resolutions

| Failures                                | Possible Reason  | Improvements  |  |
|---|--|---|--|
| Door&Indicator lose failure             | Did not get on power   | Check cable connection & power supply   |  |
| Door keep on closed and open            | Sensor detected the movement of autodoor; vibration of movement                                | Increase the antenna installation height.     check the position 3, Reduce the sensitivity. |  |
| Door don't close and blue indicator off | Switch of autodoor controller lose failure     incorrect position 3.Incorrect output of sensor | Check the switch of autodoor controller &setting of output.                                 |  |
| Door keeps on moving when it rains      | Sensor detected the actions of rain  | Adopt waterproof accessories  |  |

### 9 Technical Parameters

| Technology:      | Microwave&microwave processor                                       | Max contact power supply:         | 42V AC/60V DC                         |  |  |  |
|------------------|---|-----------------------------------|---------------------------------------|--|--|--|
| Detect mode:     | Motion detection  | Max contact current:              | 1A                                    |  |  |  |
| Detection speed: | ≥0.1meter/sec   | Output holding time:              | 1 sec, 2 sec, 3 sec, 5 sec adjustable |  |  |  |
| Pitch angle:     | 0-120 degree, 12 degree each level                                  | Working temperature:              | -25°C to+55°C                         |  |  |  |
| Detection range: | 4 * 2 meters (Installation Height 2.6 meters)                       | Working humidity:                 | 10%-90% RH(frostless)                 |  |  |  |
| LED indicators:  | When power on, blue indicator light flashes for 10s,                | Maximum installation height:      | 4 meters                              |  |  |  |
|                  | standby - Blue indicator, action - RED indicator                    | Cable length:                     | 2.5 meters                            |  |  |  |
| Power supply:    | AC 12-24V, DC 12-30V  | Sheating material:                | ABS plastic                           |  |  |  |
| Working current: | Standby 40mA, action 75mA(DC 12V)                                   | Microwave transmitting frequency: | <20dBm                                |  |  |  |
| Signal output:   | Relay 1 contact NO/NC   | Dimension:                        | 123.5(L)x57.6(W)x17(H)mm              |  |  |  |
| Packing list:    | Sensor x 1pc, instruction x 1pc, cable x 2.5 meters, screws x 1 bag |                                   |                                       |  |  |  |